

Parallel Linear Gripper

HP04L Series

Long Stroke Type

Gripping at a long point is available by the use of the linear guide.



Excellent CENTERING Accuracy

◆ $\pm 0.07\text{mm}$ or less

Piping Port on 2 faces

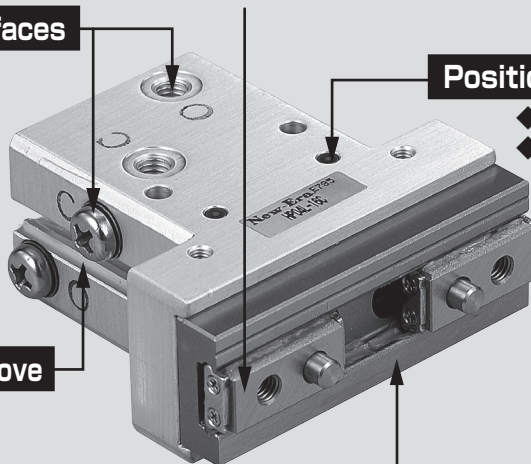
◆ Excluding $\phi 8\text{mm}$

Positioning Hole

◆ Rear Face

◆ Bottom Face

Sensor Switch Groove



About **twice**
the stroke than
the standard type

The overall length is almost same as the one of the standard type, but the stroke is double.

Use of LINEAR GUIDE

- ◆ Withstand load, withstand moment (high rigidity)
- ◆ High accuracy (repeat accuracy: $\pm 0.01\text{ mm}$ or less)
- ◆ Gripping at a long point and overhang gripping are available.

HP04L Series

Model Code No.

HP04L - 10 C ※ HAE - ZE135 A 2

Series Name

Number of Switches

Bore Size

8: 8mm
10: 10mm
16: 16mm
20: 20mm

Action Type

C : Double Acting

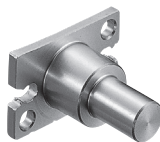
Switch Lead Wire Length

A: 1m
B: 3m

● Gripper Adaptor Type
No Code: No Gripper Adaptor

HAE

HFE (excluding $\phi 8$)
HFE-L : Large Diameter Type
($\phi 16$ only)



● Detailed specifications → P.28~29

● Switch Type No Code: No Switch

ZE135 ES13

2 Wire System Solid State Switch, Straight Type

ZE155 ES(P)15

3 Wire System Solid State Switch, Straight Type



ZE235 ES23

2 Wire System Solid State Switch, L-shaped

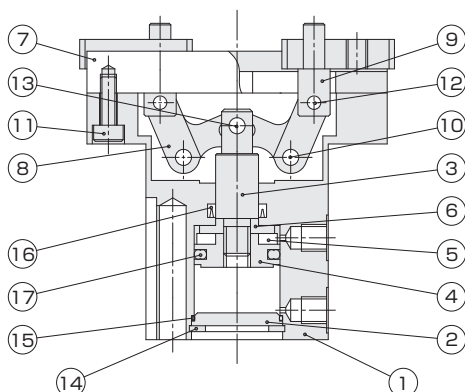
ZE255 ES(P)25

3 Wire System Solid State Switch, L-shaped



● Switch details → P.521~528

Internal Structure Diagram



Parts List

NO	Name	Material
1	Main Body	Aluminum Alloy
2	Head Cover	Aluminum Alloy
3	Piston Rod	Stainless Steel
4	Piston	Aluminum Alloy
5	Magnet	Resin
6	Pressure Cover	Aluminum Alloy
7	Linear Guide	Bearing Steel
8	Action Lever	Carbon Steel
9	Knuckle	Stainless Steel
10	Fulcrum Pin	Carbon Tool Steel
11	Hexagon Socket Head Bolt	Stainless Steel
12	Press Fit Pin	Carbon Tool Steel
13	Press Fit Pin	Carbon Tool Steel
14	Hole Locating Snap Ring	Carbon Tool Steel
15	O Ring	NBR
16	Rod Packing	NBR
17	Piston Packing	NBR

Specifications

Fluid	Air
Maximum Operating Pressure [MPa]	0.7
Proof Pressure [MPa]	1.05
Operating Temperature [°C]	0~60 (No Freezing)
Lubrication	Not Required (Required for sliding parts of the machine) Only $\phi 8$ required
Pipe Bore	M3×0.5 (HP04L-8, HP04L-10) M5×0.8 (HP04L-16, HP04L-20)
Maximum Operating Cycle [Cycle/min]	120
Centering Accuracy [mm]	±0.07
Repeat Accuracy [mm]	±0.01
Applicable Switch	ZE, ES Type (Solid State Switch)

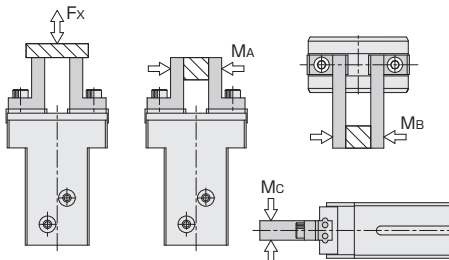
Action Type	Model	Bore Size [mm]	Minimum Operating Pressure [MPa]	Opening/Closing Stroke [mm]	Gripping Force [N]		Outside Dimensions (T x W x L) [mm]	Product Mass [g]
					Close	Open		
Double Acting	HP04L-8C	8	0.22	8	5.8	9.9	13×26×32	27
	HP04L-10C	10	0.2	12	10	15.6	20×45×49	90
	HP04L-16C	16	0.12	16	26	39	25×56×56	168
	HP04L-20C	20	0.1	22	45	60	32×73×73	368

Note) The grip force is measured at the intermediate position of the opening/closing stroke. It is an effective value when the grip point L is 30 mm and the pressure is 0.5 MPa.

The opening force of the single acting type indicates the spring force.

When this product is used with an extremely short stroke, it may work badly because of the lack of oil of the guide.

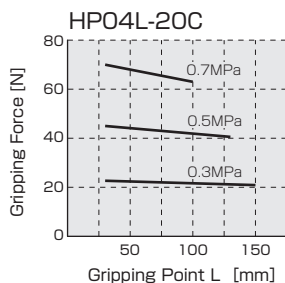
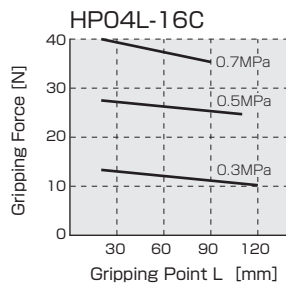
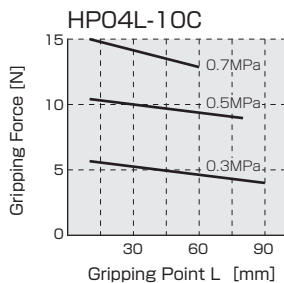
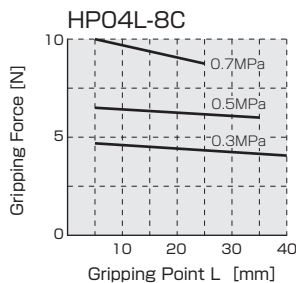
Allowable Load and Allowable Moment



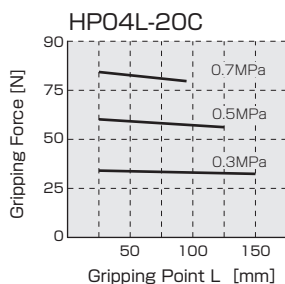
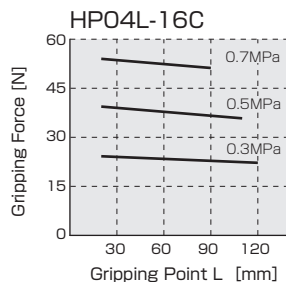
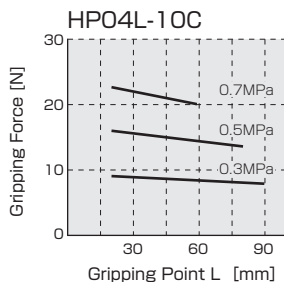
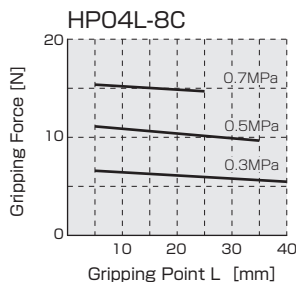
Model \ Load and Moment	Fx [N]	MA [N·m]	MB [N·m]	MC [N·m]
HP04L-8	12	0.04	0.04	0.08
HP04L-10	50	0.4	0.4	0.8
HP04L-16	120	1	1	2
HP04L-20	200	1.5	1.5	3

Effective Gripping Force

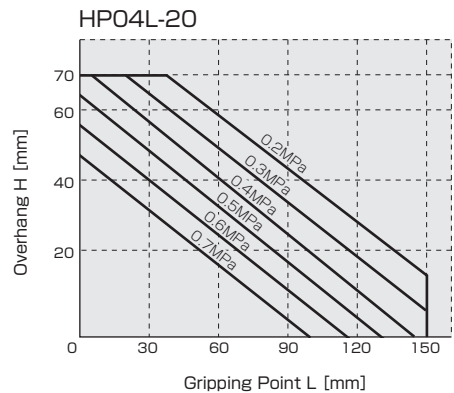
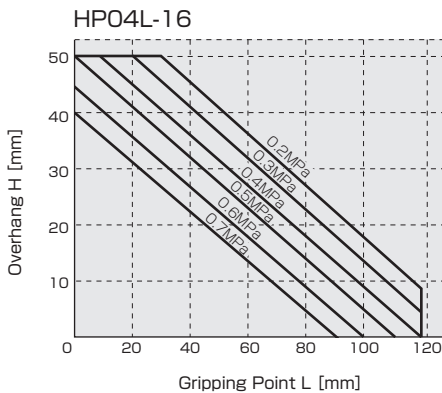
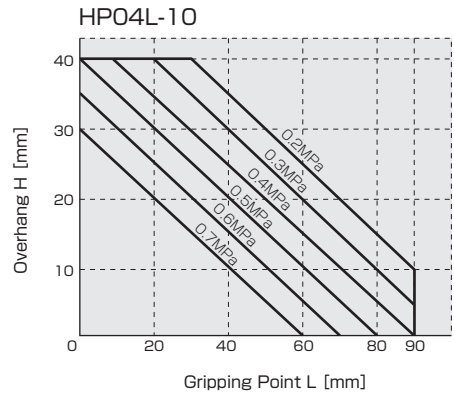
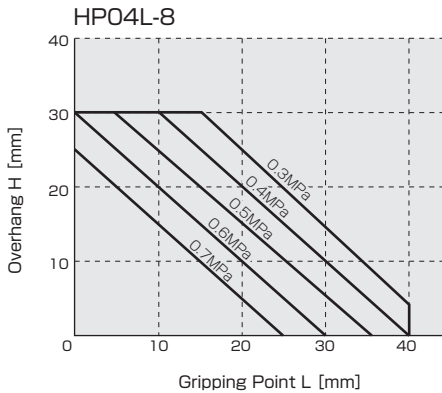
Closing Force (Double Acting Type)



Opening Force (Double Acting Type)



Gripping Point Limit Range

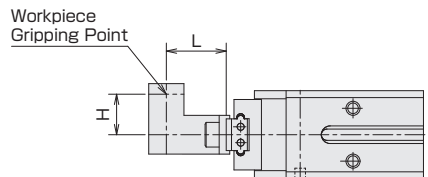


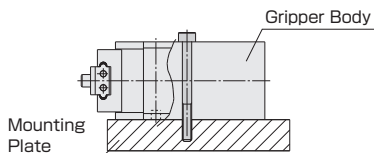
● Mounting of the attachment

L (distance gripping point) and H (overhang distance) of the attachment to be mounted to the lever shall be within the range specified in the above drawing (Gripping point limit range). If they exceed the limit range, excess moment will be applied to the guide, causing troubles that have a bad influence on the life and accuracy (e.g. finger backlash). Even if they are within the limit range, the attachment shall be as small and light as possible.

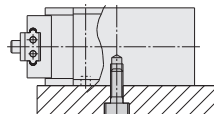
● Guide for selecting a model for the workpiece weight

It shall be 5 to 10% of the effective gripping force or any value less than that although it differs depending on the coefficient of friction between the attachment and the workpiece and the shape. It shall be greater than that when great acceleration or impact is applied during workpiece transportation.

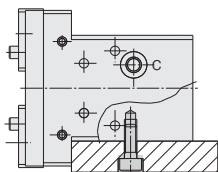


Main Body Mounting Method**Mounting Example****1** When the through-hole of the main body is used(Switch not mountable for $\phi 10$, $\phi 16$ and $\phi 20$)

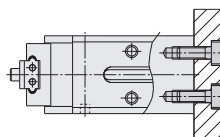
Model	Bolt to be Used	Maximum Tightening Torque[N·m]
$\phi 8$	M3×0.5	0.59
$\phi 10$	M3×0.5	0.59
$\phi 16$	M3×0.5	0.59
$\phi 20$	M4×0.7	1.37

2 When the screw on the back face of the main body is used(Excluding $\phi 8$)

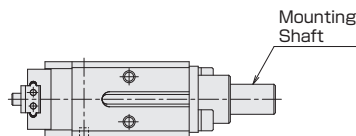
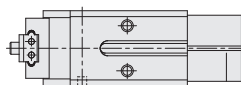
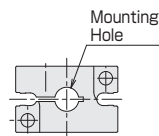
Model	Bolt to be Used	Maximum Tightening Torque[N·m]
$\phi 10$	M4×0.7	1.37
$\phi 16$	M4×0.7	1.37
$\phi 20$	M5×0.8	2.84

3 When the screw on the side of the main body is used

Model	Bolt to be Used	Maximum Tightening Torque[N·m]
$\phi 8$	M3×0.5	0.59
$\phi 10$	M3×0.5	0.59
$\phi 16$	M4×0.7	1.37
$\phi 20$	M5×0.8	2.84

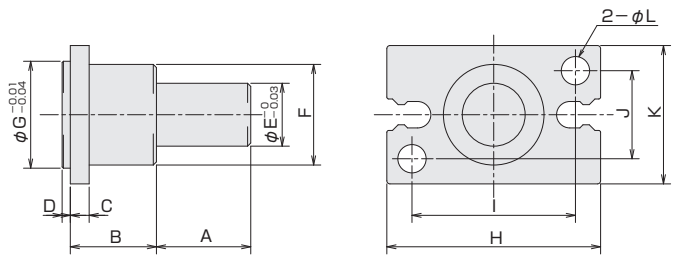
4 When the screw on the bottom face of the main body is used(Only $\phi 8$ requires a space such as a relief because the switch protrudes.)

Model	Bolt to be Used	Maximum Tightening Torque[N·m]
$\phi 8$	M2.5×0.4	0.34
$\phi 10$	M3×0.5	0.59
$\phi 16$	M4×0.7	1.37
$\phi 20$	M5×0.8	2.84

5 When a gripper adaptor is used for mounting**HAE Type****HFE, HFE-L Type**(Excluding $\phi 8$)

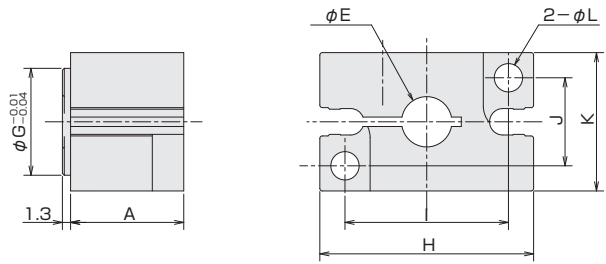
■ Outline Dimensional Drawing of Gripper Adaptor

HAE Type

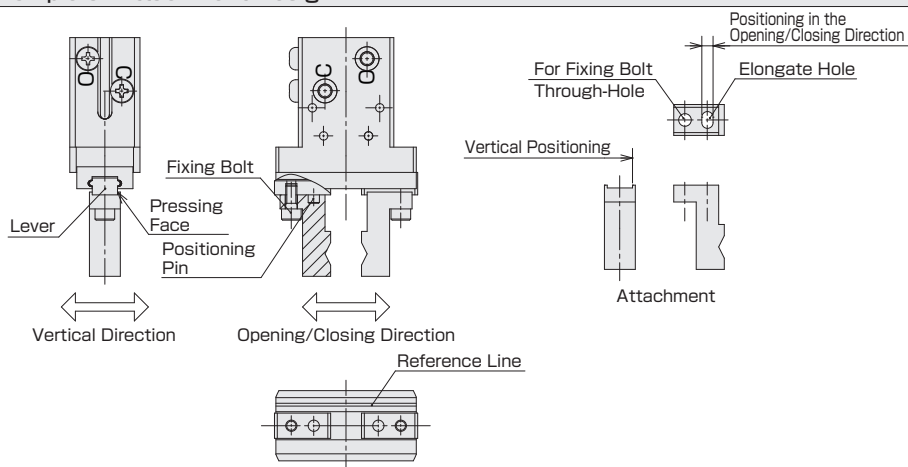
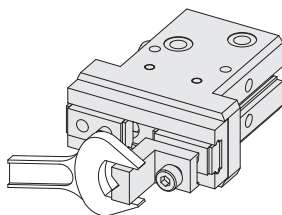


Type	Code	A	B	C	D	E	F	G	H	I	J	K	L	Ancillary Bolt (x2)	Product Mass[g] (Including Bolts)
HAE-8		10	10	3	0.8	8	10	9	20	15	9	13	2.8	M2.5×0.45×6 ^L	6
HAE-10		15	15	3	1.3	10	11	11	23	17	10	16	3.4	M3×0.5×8 ^L	11
HAE-16		15	15	3	1.3	10	16	17	34	26	14	22	4.5	M4×0.7×10 ^L	20
HAE-20		15	15	3	1.3	10	18	21	45	35	16	26	5.5	M5×0.8×10 ^L	28

HFE Type



Type	Code	A	E	G	H	I	J	K	L	Ancillary Bolt (x3)		Product Mass[g] (Including Bolts)
HFE-10		15	6	11	23	17	10	16	3.4	M3×0.5×16 ^L	M3×0.5×12 ^L	14
HFE-16		18	8	17	34	26	14	22	4.5	M4×0.7×20 ^L	M4×0.7×16 ^L	35
HFE-16L		18	10	17	34	26	14	22	4.5	M4×0.7×20 ^L	M4×0.7×16 ^L	33
HFE-20		19	13	21	45	35	16	26	5.5	M5×0.8×20 ^L	M5×0.8×20 ^L	55

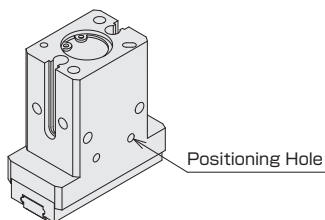
Attachment Design Method**Example of Attachment Design****Attachment Mounting Method**

When you mount the attachment, hold the attachment with a spanner or the like to remove load to the lever.

Model	Bolt to be Used	Maximum Tightening Torque[N·m]
φ8	M2×0.4	0.315
φ10	M3×0.5	1.14
φ16	M4×0.7	2.7
φ20	M5×0.8	5.4

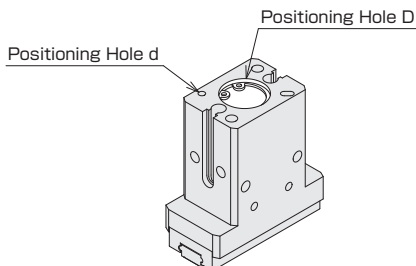
Positioning Hole

Positioning Hole for Mounting Examples 1 and 2 (P.28)



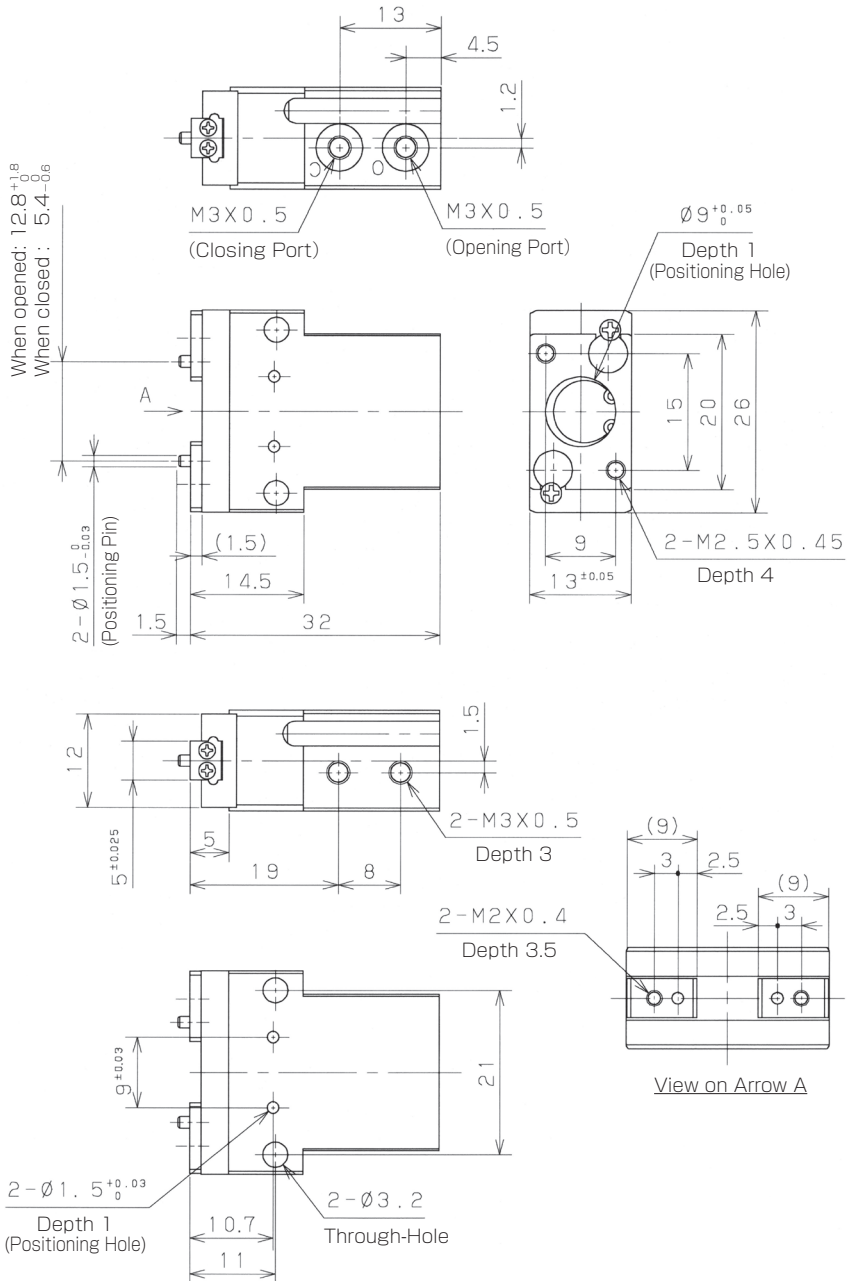
Model	Positioning Hole
φ8	$\phi 1.5^{+0.02}_0$ depth 1
φ10	$\phi 2.5^{+0.02}_0$ depth 2.5
φ16	$\phi 3^{+0.02}_0$ depth 3
φ20	$\phi 4^{+0.02}_0$ depth 3.5

Positioning Hole for Mounting Examples 4 (P.28)

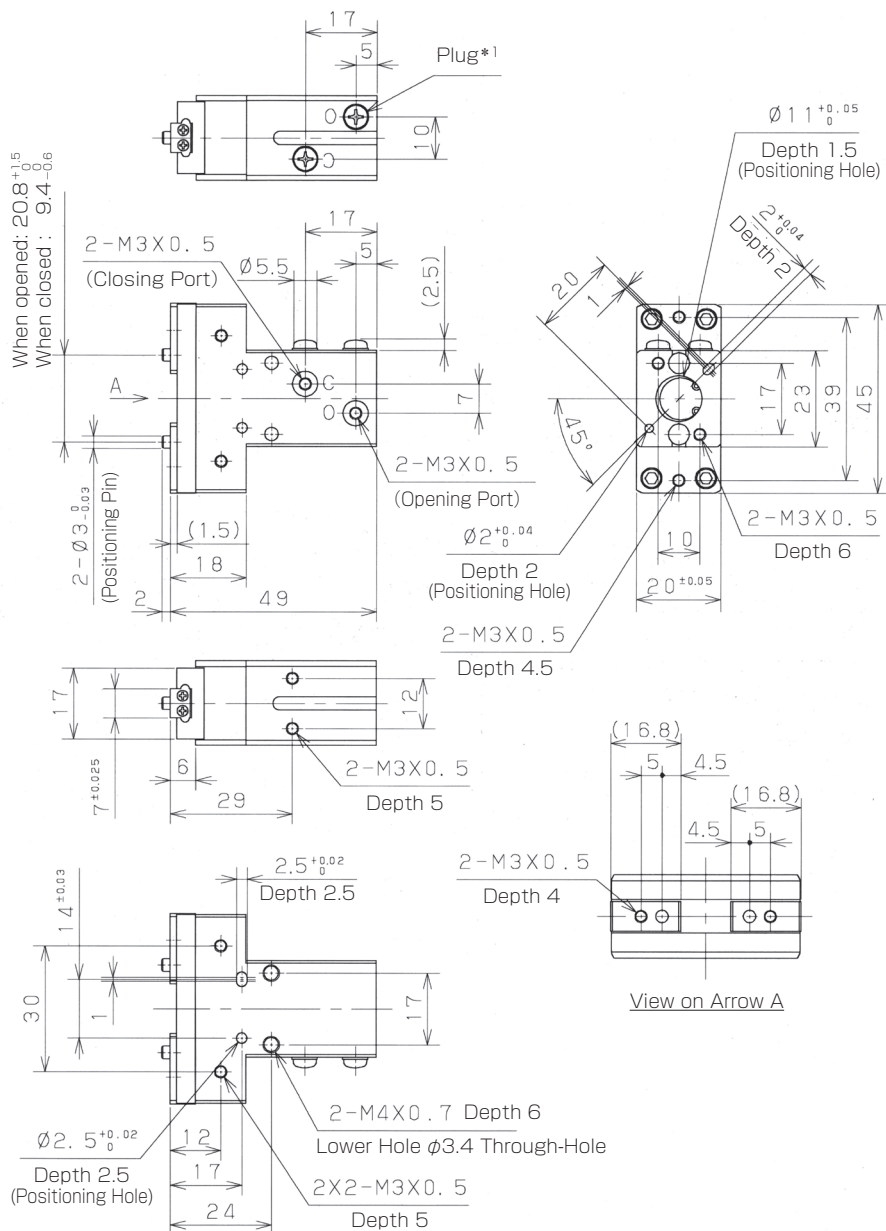


Model	Positioning Hole D	Positioning Hole d
φ8	$\phi 9^{+0.05}_0$ depth 1.5	—
φ10	$\phi 11^{+0.05}_0$ depth 1.5	$\phi 2^{+0.04}_0$ depth 2
φ16	$\phi 17^{+0.05}_0$ depth 1.5	$\phi 2.5^{+0.04}_0$ depth 3
φ20	$\phi 21^{+0.05}_0$ depth 1.5	$\phi 3^{+0.04}_0$ depth 3

Dimensions HP04L-8C



Dimensions HP04L-10C

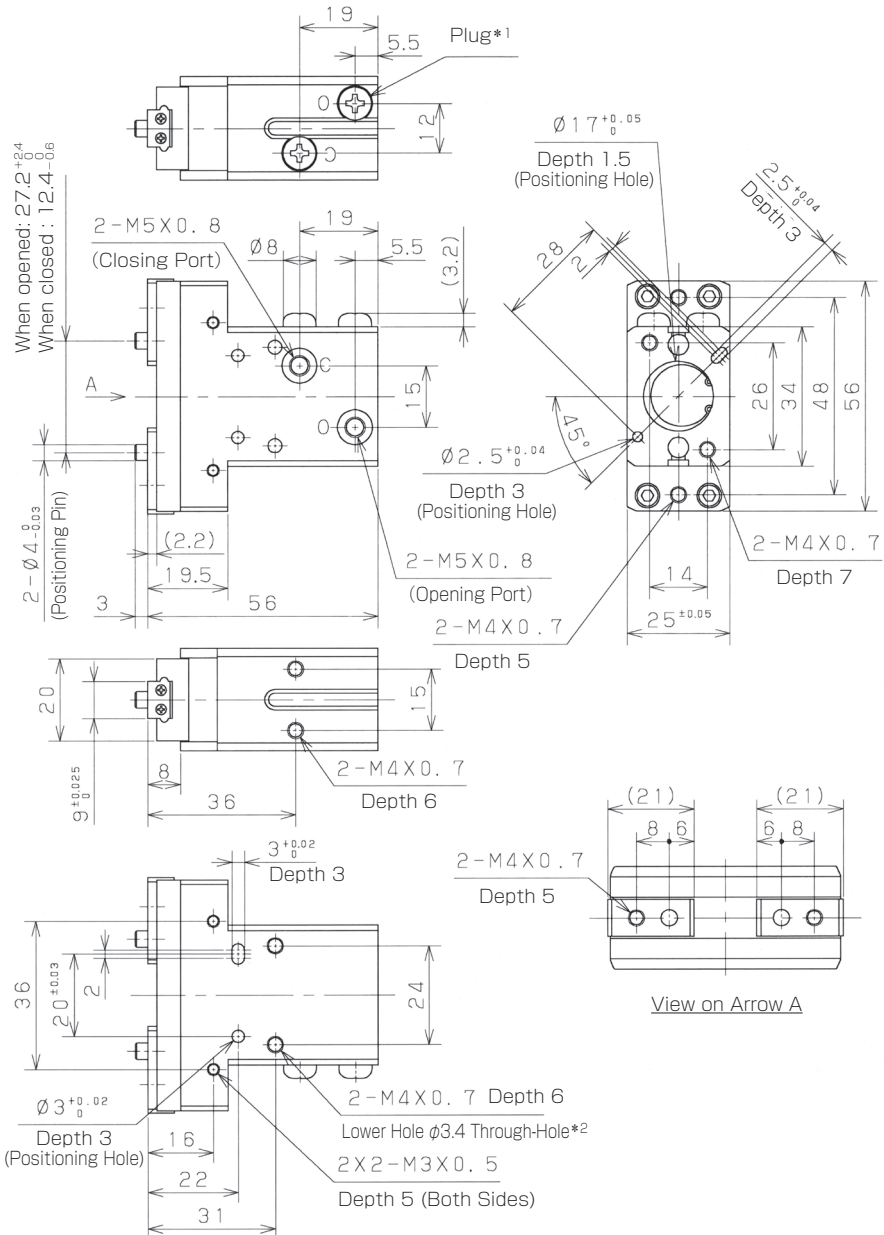


*1) Two faces have an air port. Select the one you use according to the mounting condition.

*2) Note that when the main body is mounted using the through-hole, you cannot mount the opening side sensor.

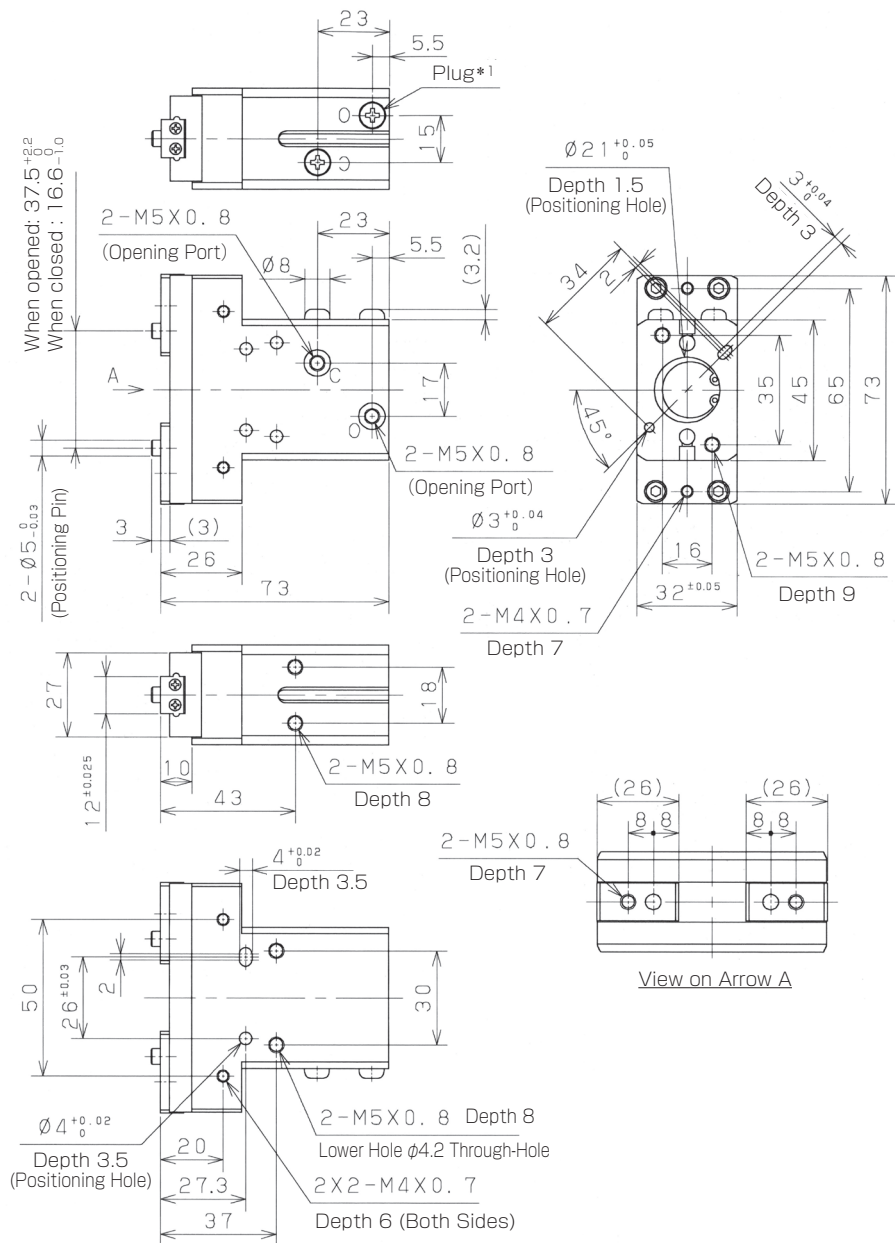
HP04L Series

Parallel Linear Gripper (Long Stroke Type)



*2) Note that when the main body is mounted using the through-hole, you cannot mount the opening side sensor.

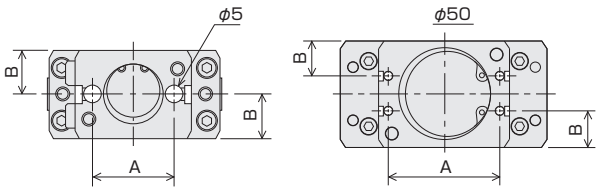
Dimensions **HP04L-20C**



*1) Two faces have an air port. Select the one you use according to the mounting condition.

*2) Note that when the main body is mounted using the through-hole, you cannot mount the opening side sensor.

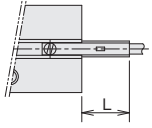
Switch Groove Dimensions



Code	Size	8	10	16	20
A		15	17	24	30
B		3	10	12.5	16

Switch Protrusion Distance

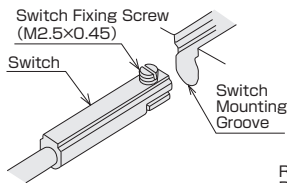
The maximum switch protrusion from the switch body end face (when the levers are full closed) is shown in the table below. Use it as a guide for mounting.



Cylinder Bore (mm)	φ8	φ10	φ16	φ20
Maximum Protrusion (mm)	2	0	0	0

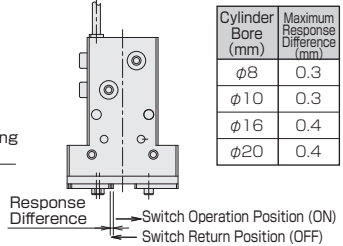
Switch Mounting

Insert the switch into the switch mounting groove. After setting the mounting position, tighten the switch fixing screw with a precision screwdriver. The tightening torque shall be 0.1 N·m or less.



Switch Response Difference

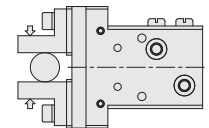
The distance from the position where the levers move and the switch turns on to the position where the levers move in the reverse direction and the switch turns off is called 'response difference'.



Cylinder Bore (mm)	Maximum Response Difference (mm)
φ8	0.3
φ10	0.3
φ16	0.4
φ20	0.4

Switch Mounting Position Adjustment Method

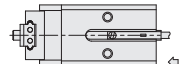
For external gripping



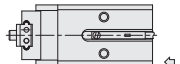
①Check the workpiece external gripping and full close.



②Insert the switch into the switch mounting groove of the main body in the arrow direction.

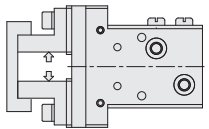


③The LED lamp lights up by turning on the switch in the arrow direction.



④Fix the switch by a switch fixing screw at the position where the switch is moved 0.6 mm in the arrow direction from the position where the lamp lights up in [3].

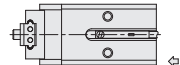
For internal gripping



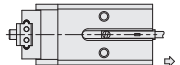
①Check the workpiece internal gripping and full opening.



②Insert the switch into the switch mounting groove of the main body in the arrow direction.



③The LED lamp lights up by moving the switch in the arrow direction. It goes off by moving it further.



④Fix the switch at the position that is 0.6 mm moved from the position where the LED lamp lights up when it is returned in the arrow direction (reverse direction) in [3].

①Indicates the position where you need to check if the switch is ON. Mount the switch by adjusting it in the order from ① to ④.